



1ST LIAISE CONFERENCE AND  
DETERMINING EVAPOTRANSPIRATION  
CROSSCUT WORKSHOP

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# Classification of Different Irrigation Systems at Field Scale Using Annual Time-Series of Remote Sensing Data

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## Why obtaining classification maps of irrigation systems? Mitigating water demands

1. Currently there is no precise/reliable information regarding irrigated area and irrigation systems in Catalonia
2. Replace the simplistic assumption of irrigation scenarios used in many Land Surface Models (LSM). -> reduce uncertainty.
3. Promote and supervise the shift towards more sustainable and efficient irrigation methods. -> optimize water use.

FLOOD



SPRINKLER



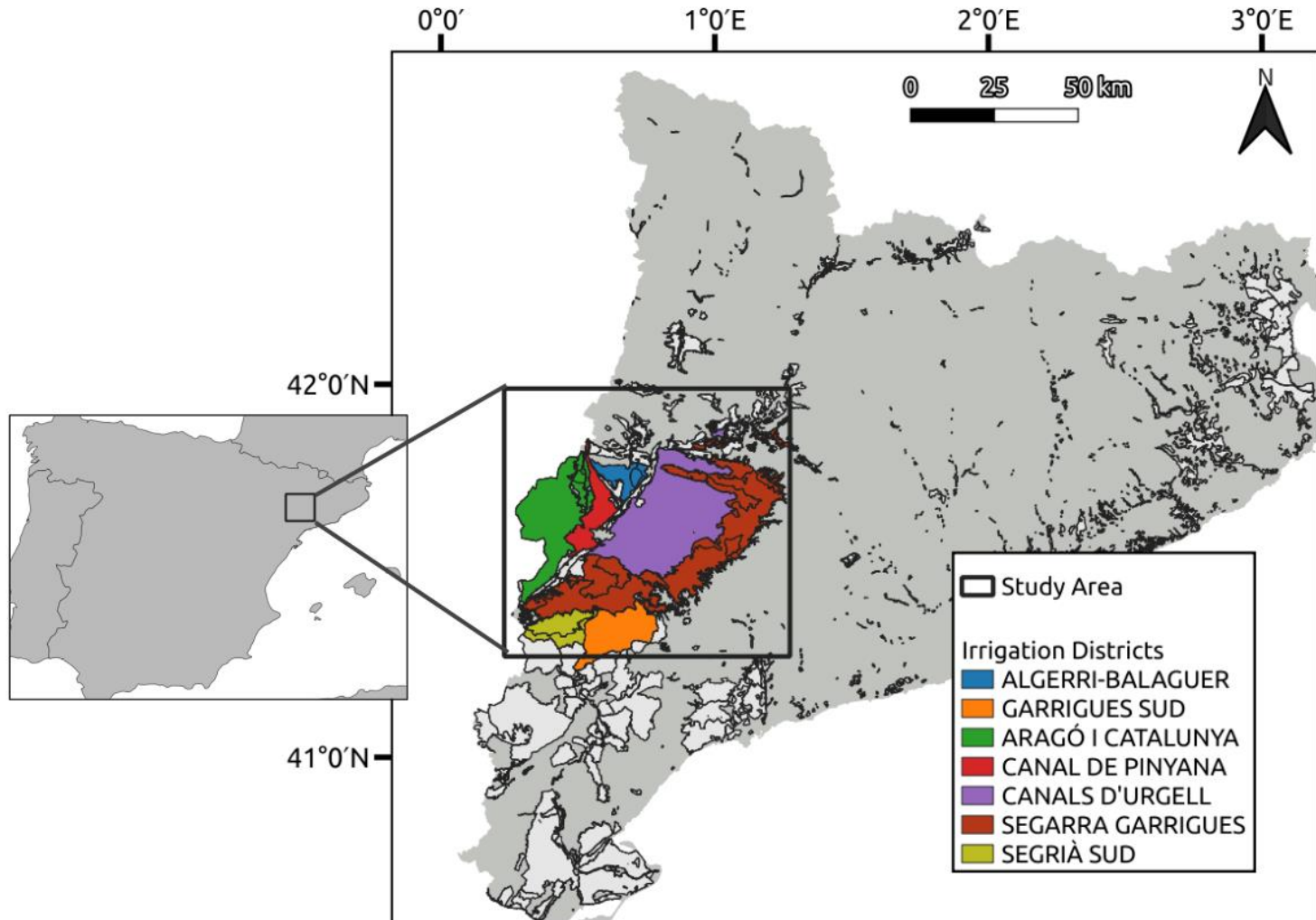
DRIP



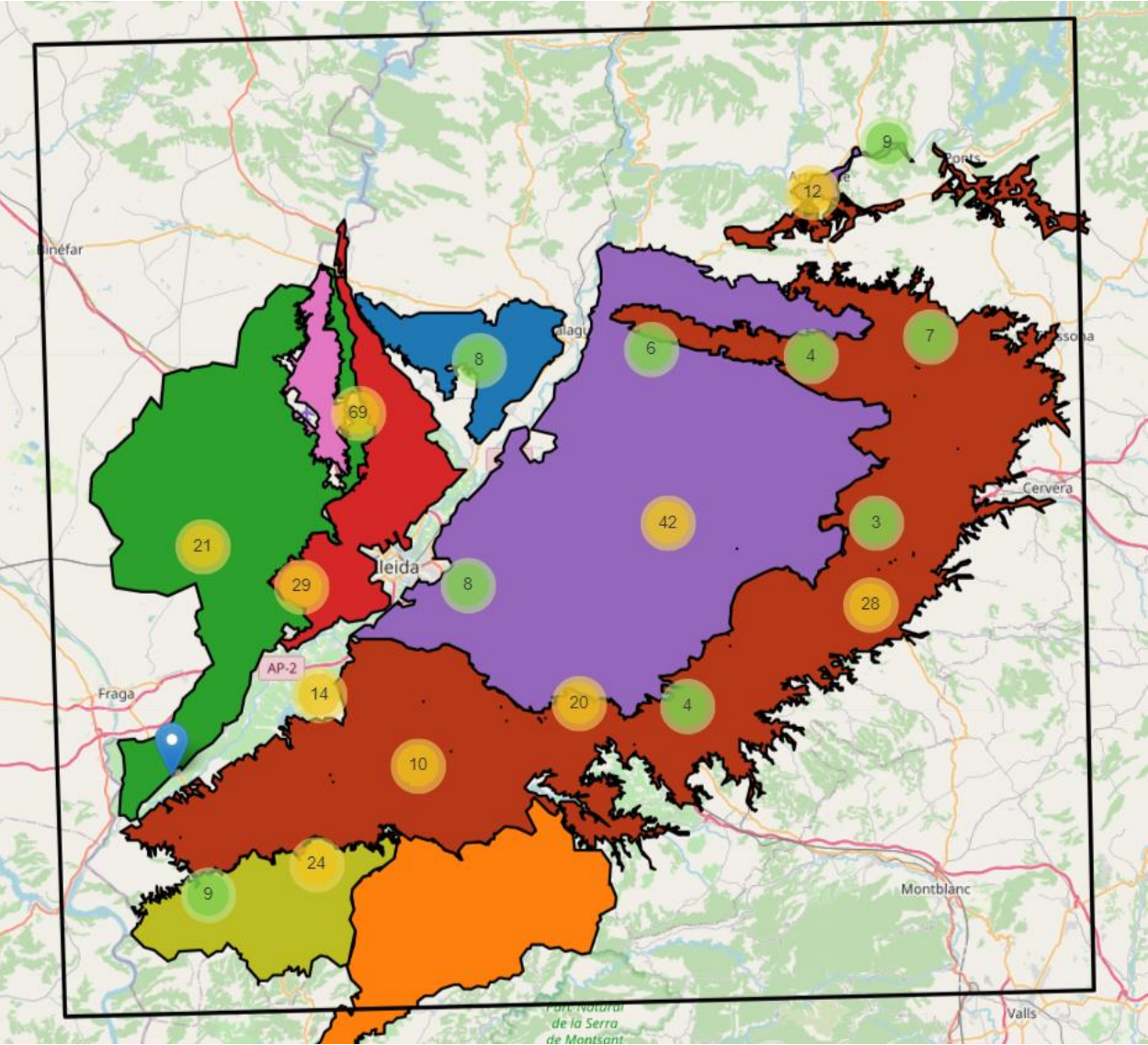
## Hypothesis of Study

Temporal series of actual crop evapotranspiration, and surface soil moisture (estimated from remote sensing) should vary among parcels of different irrigation systems

# Study Area



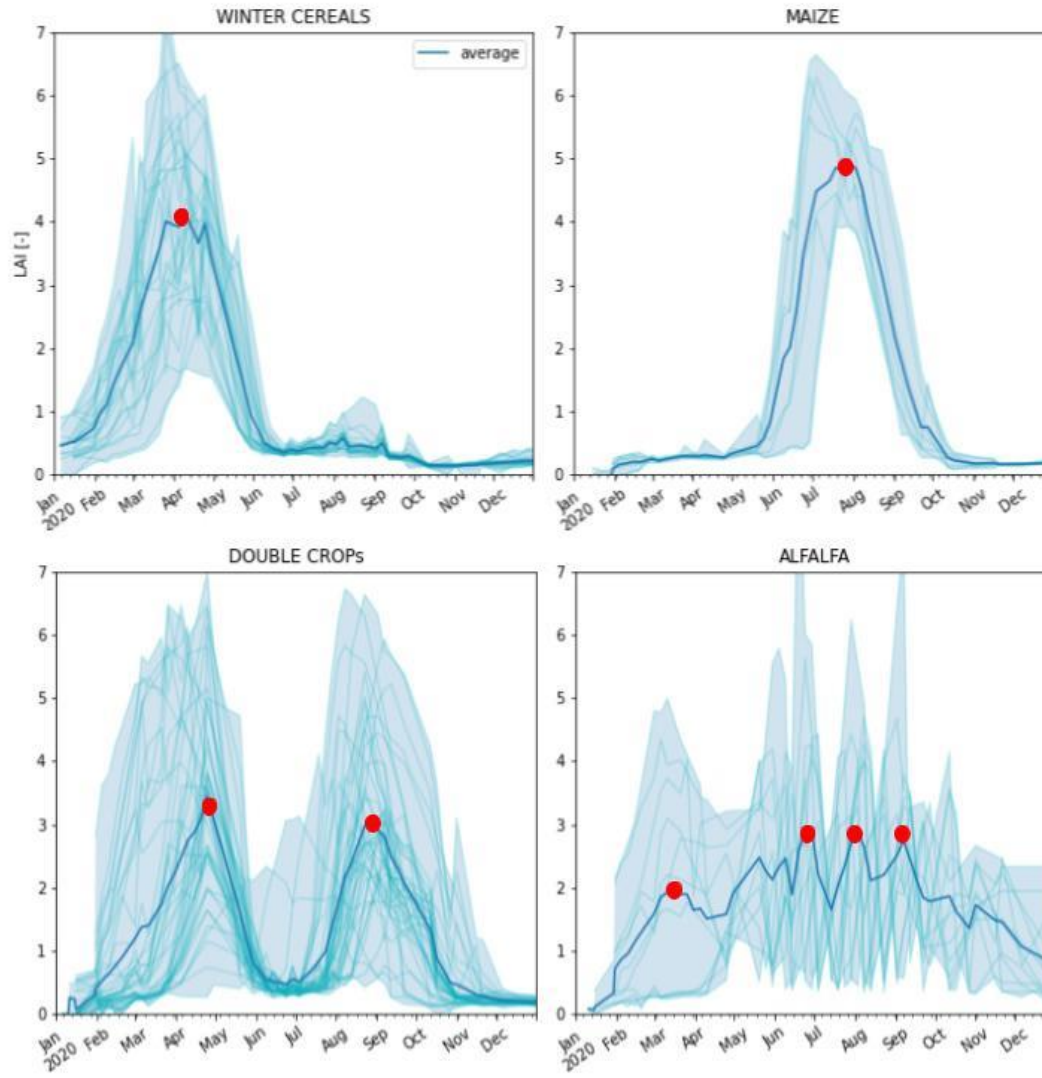
# Field Campaign - Distribution of Fields



> 300 fields

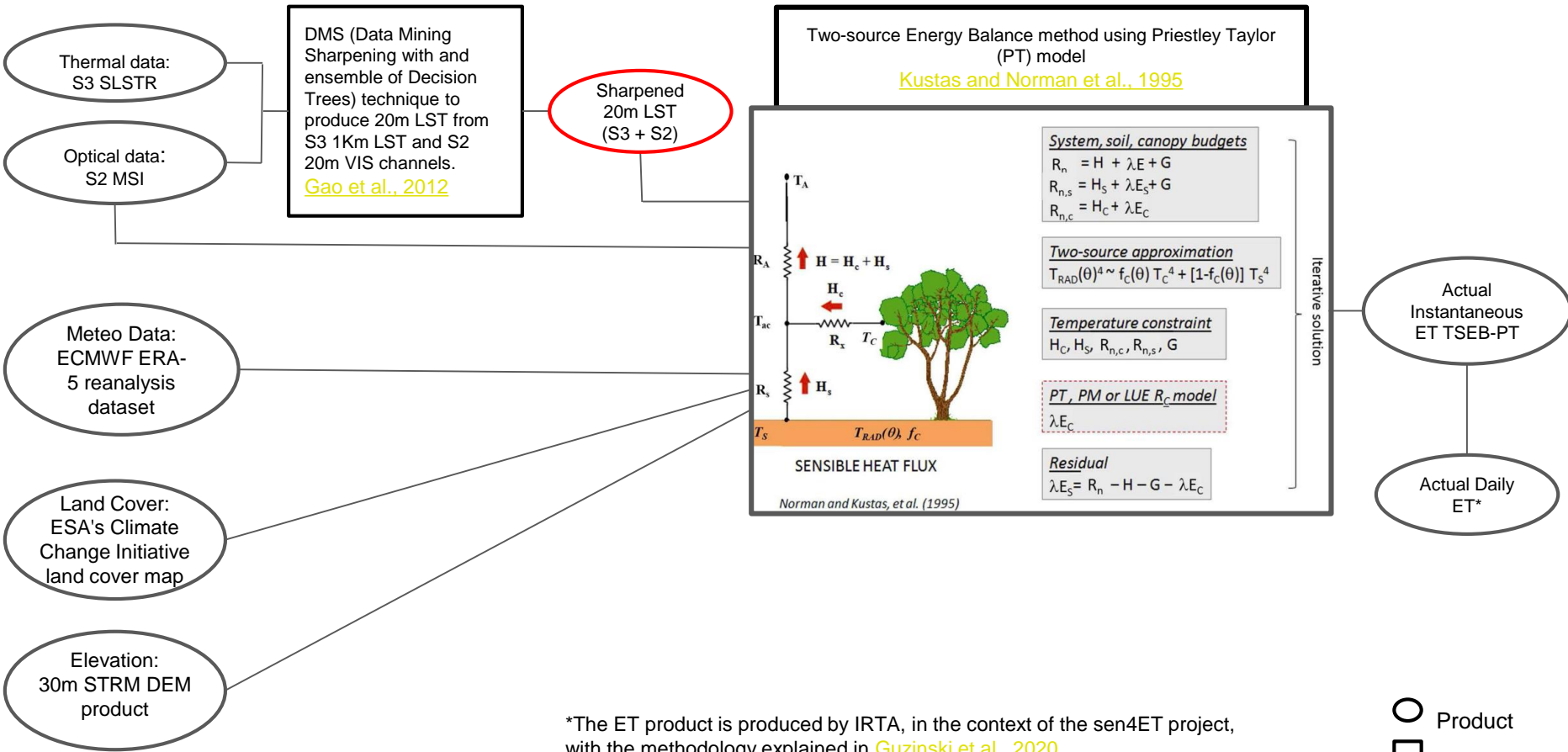


# Field Campaign - Crop Detection



# Field Campaign - Number of Fields

IRRIGATION SYSTEM	CROP TYPE	Number of Fields			FIELD LEVEL	PIXEL LEVEL
		2018	2019	2020		
DRIP	FRUIT and NUT TREES	78	78	78	234	24201
	VINEYARD	12	12	12	36	4599
	OLIVE	11	11	11	33	3201
SPRINKLER	MAIZE	8	8	8	24	10950
	DOUBLE CROPS	55	56	56	167	43849
	ALFALFA	7	7	7	21	3777
FLOOD	WINTER CEREALS	9	9	9	27	444
	MAIZE	14	14	13	41	1322
	DOUBLE CROPS	32	33	33	98	5859
	ALFALFA	9	9	9	27	2733
	FRUIT and NUT TREES	18	18	18	54	1734
NOT IRRIGATED	WINTER CEREALS	40	36	40	116	27584
	FRUIT and NUT TREES	13	13	13	39	1578
	VINEYARD	7	7	7	21	867
	OLIVE	17	17	17	51	6231
TOTAL		330	328	331	989	138929

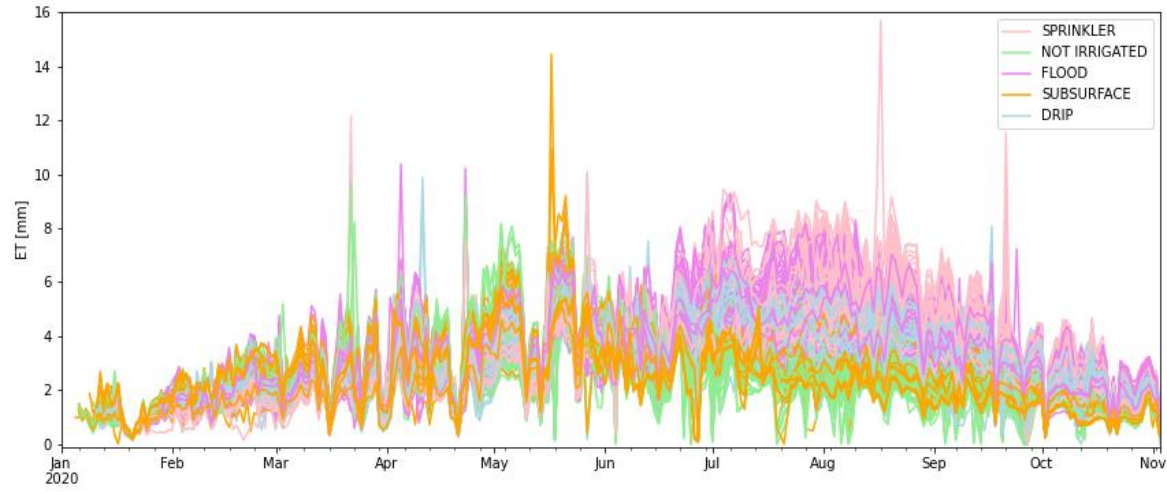
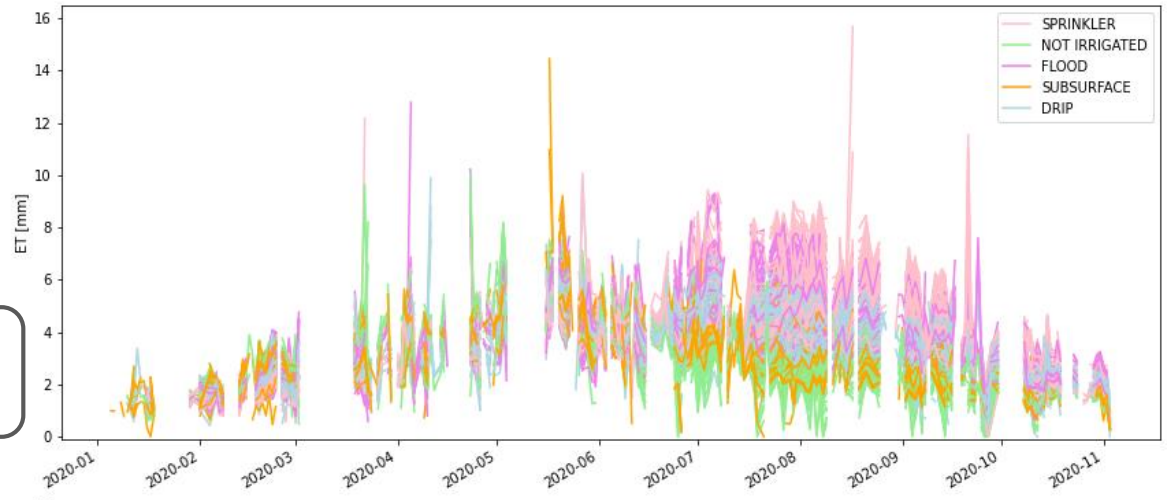
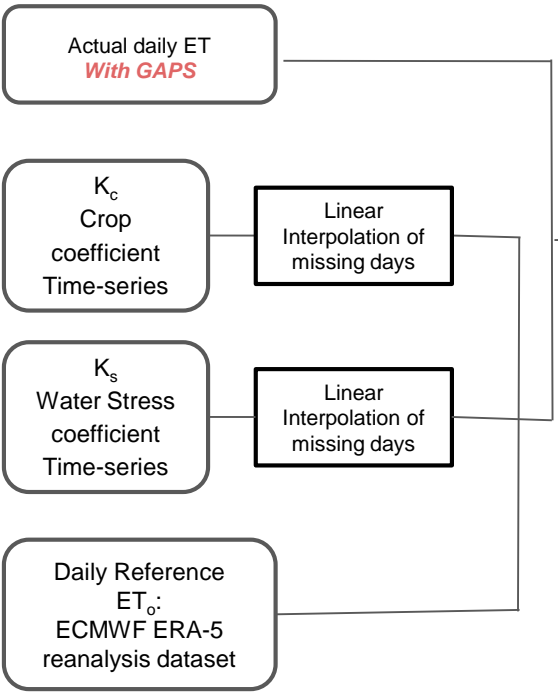


\*The ET product is produced by IRTA, in the context of the sen4ET project, with the methodology explained in [Guzinski et al., 2020](#).

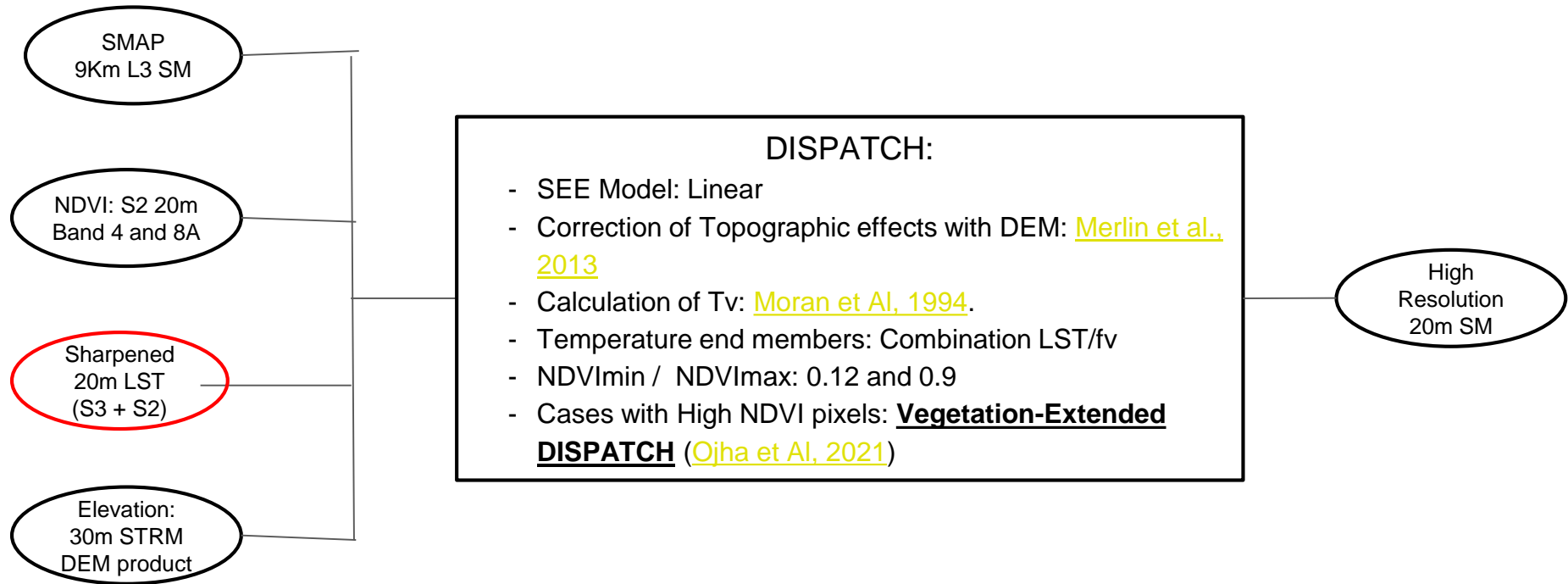
○ Product  
 □ Process



# Input ETact



# Input Dispatch SM



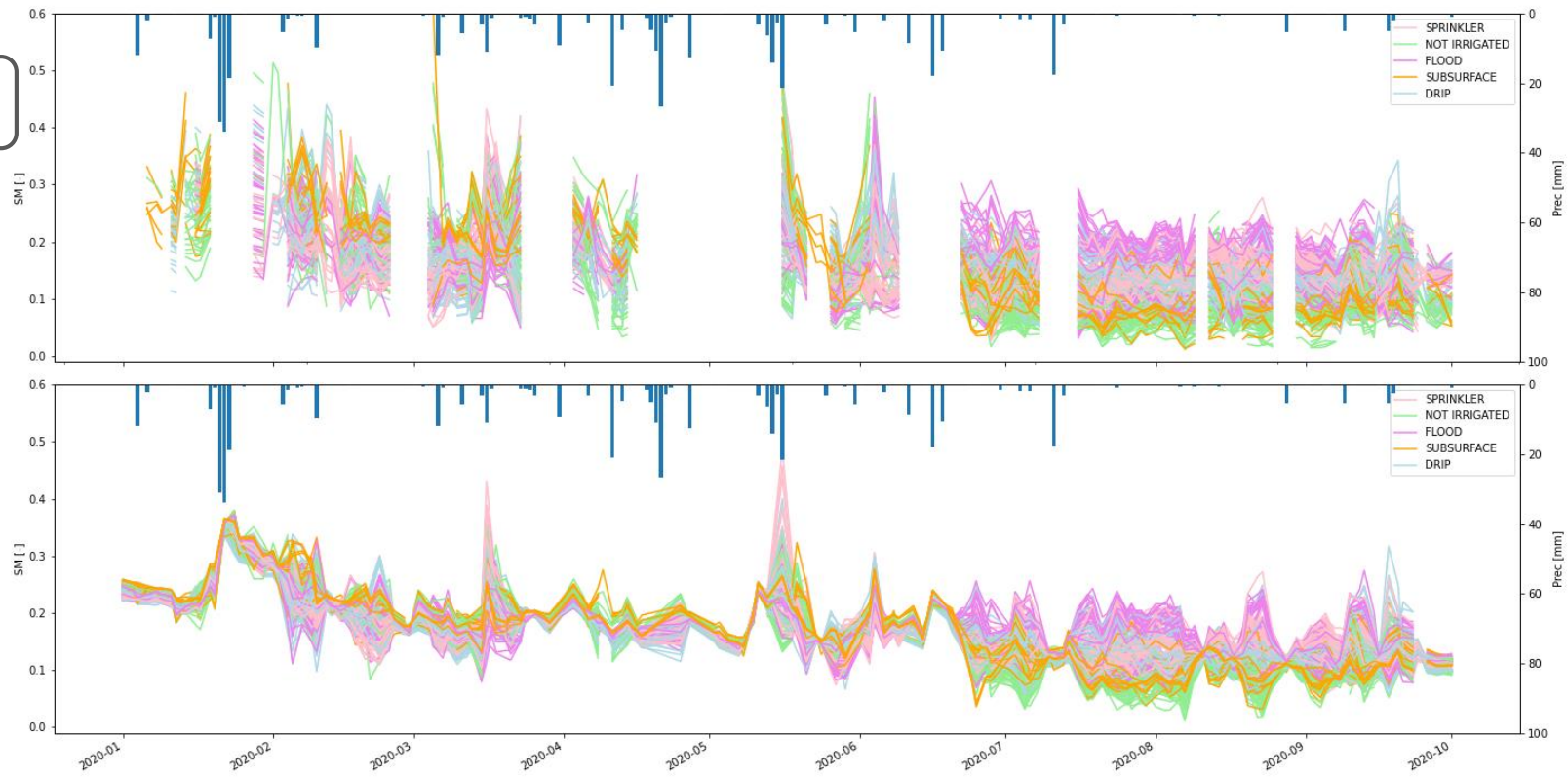
On going validation of the product with in-situ SM values in different sites in the area...

# Input Dispatch SM

Dispatch 20m SM  
*With GAPS*

SMAP 9 Km  
SM

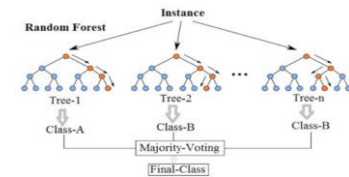
Dispatch  
20m SM  
*Filled*



# AI models tested

TABLE IV  
OVERVIEW OF THE MODELS USED IN THIS STUDY

MODELS	Reason for selection
Time Series Forest	Random forest is widely used in similar research [14]. Used as a benchmark.
ROCKET	State-of-the-art accuracy [39] with low computational requirements.
ResNet	Deep neural network with flexible structure, it outperforms other models in general reviews [40].



ROCKET	
length	{7, 9, 11}
weights	$\mathcal{N}(0, 1)$
bias	$\mathcal{U}(-1, 1)$
dilation	random
padding	random

Convolutional neural network

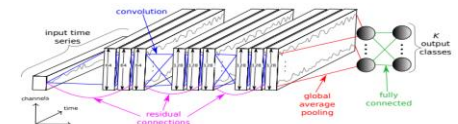


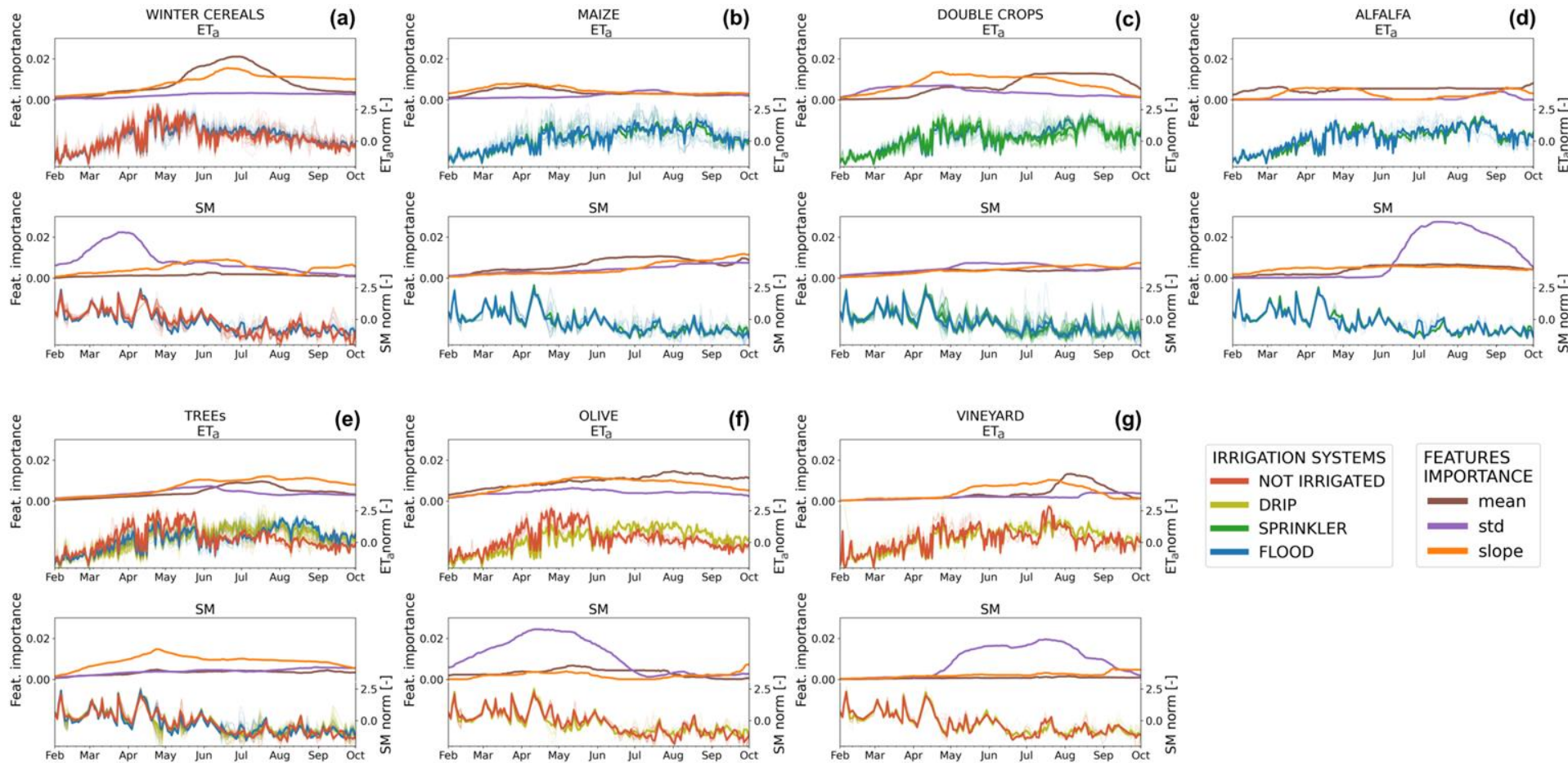
Fig. 6: The Residual Network's architecture for time series classification.

# Results I

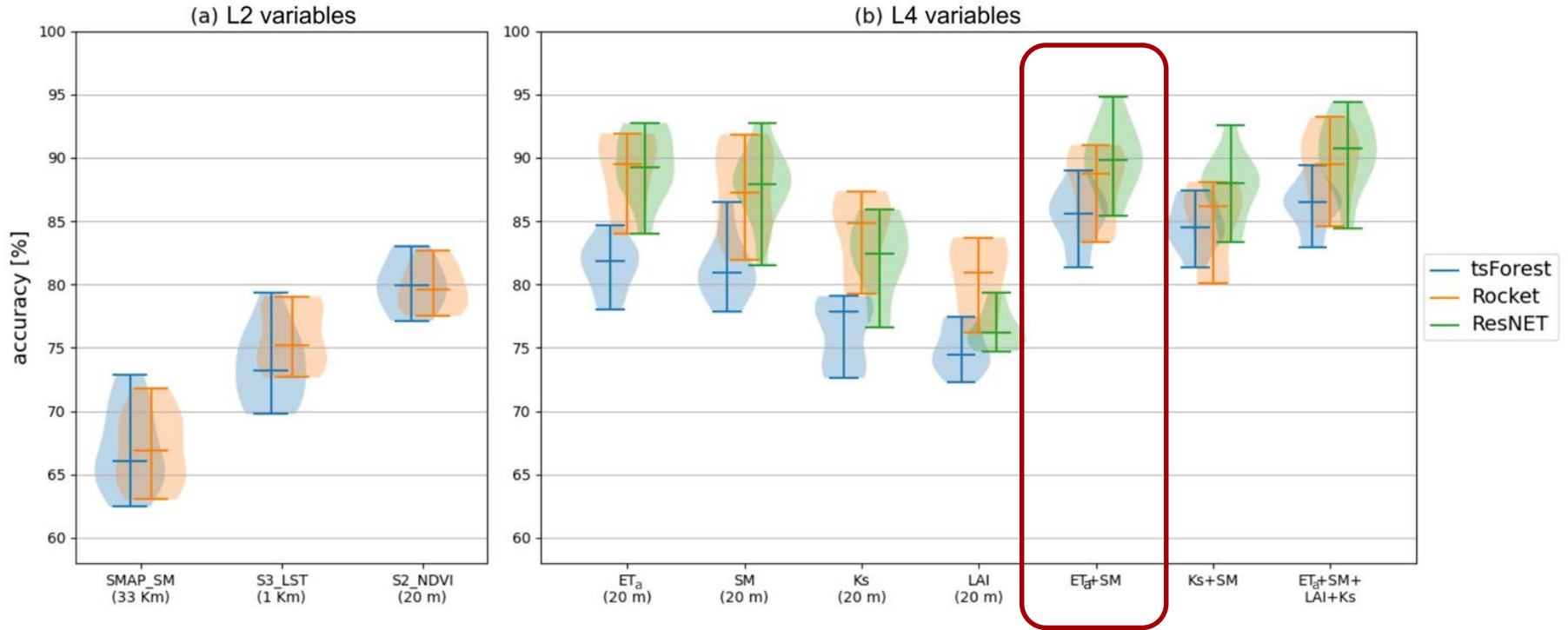
Is the irrigation system only explained by the crop type?

Variables	Crop types							RESULTS	
	Winter Cereals	Maize	Double Crops	Alfalfa	Fruit & Nut Trees	Olives	Vineyards	Aggregated Models	General Model
$ET_a$ -TSEB	81.25%	48.82%	91.67%	72.00%	74.88%	<b>74.33%</b>	96.19%	78.15%	79.33%
SM Dispatch	88.75%	<b>76.47%</b>	91.67%	66.67%	73.18%	73.33%	80.95%	78.36%	74.25%
$ET_a$ +SM	<b>90.62%</b>	70.00%	<b>93.75%</b>	<b>73.33%</b>	<b>81.71%</b>	69.67%	96.67%	<b>83.39%</b>	<b>81.89%</b>

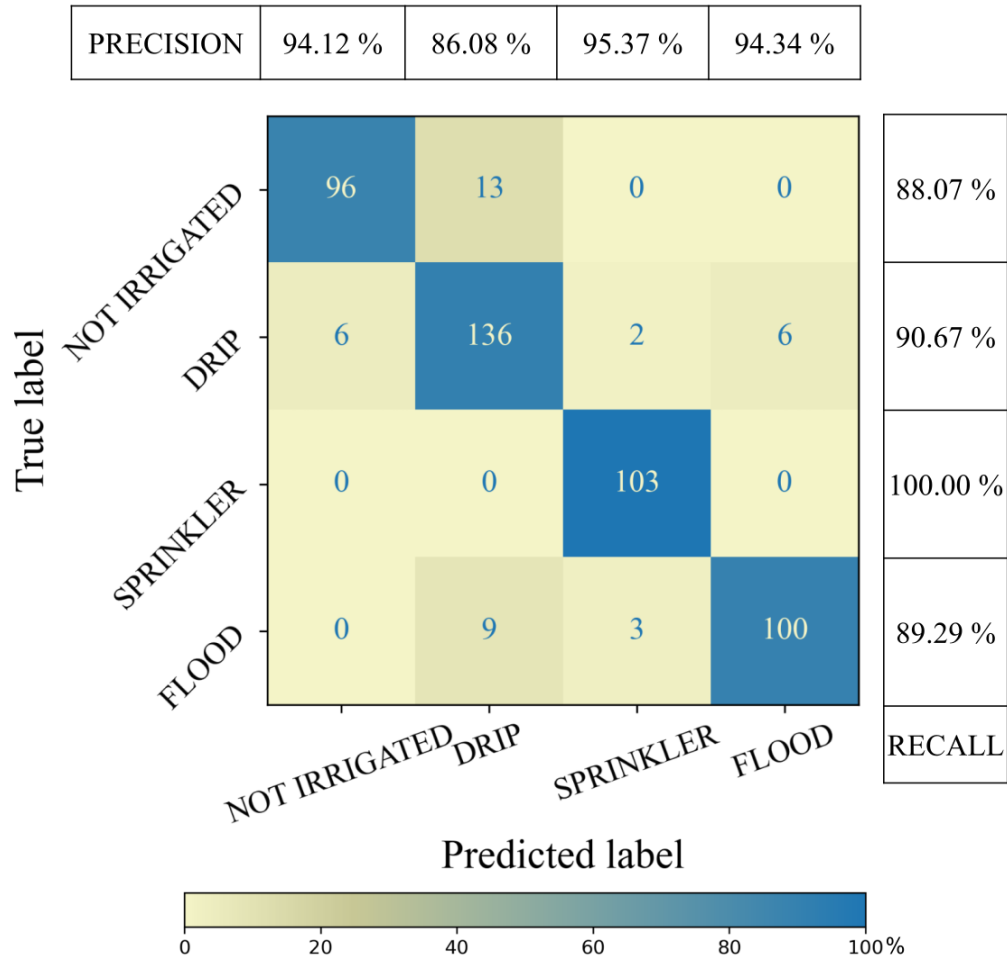
# Results II



# Results III



# Results IV



METRICS (%)	MODELS		
	tsForest	ROCKET	ResNET
Accuracy	85.29 ± 2.41	87.56 ± 2.95	<b>90.10 ± 2.70</b>
Average Precision	85.43 ± 2.53	88.80 ± 3.12	<b>90.33 ± 2.78</b>
Average Recall	84.76 ± 2.51	86.81 ± 3.17	<b>90.02 ± 2.76</b>



# Maps irrigation systems

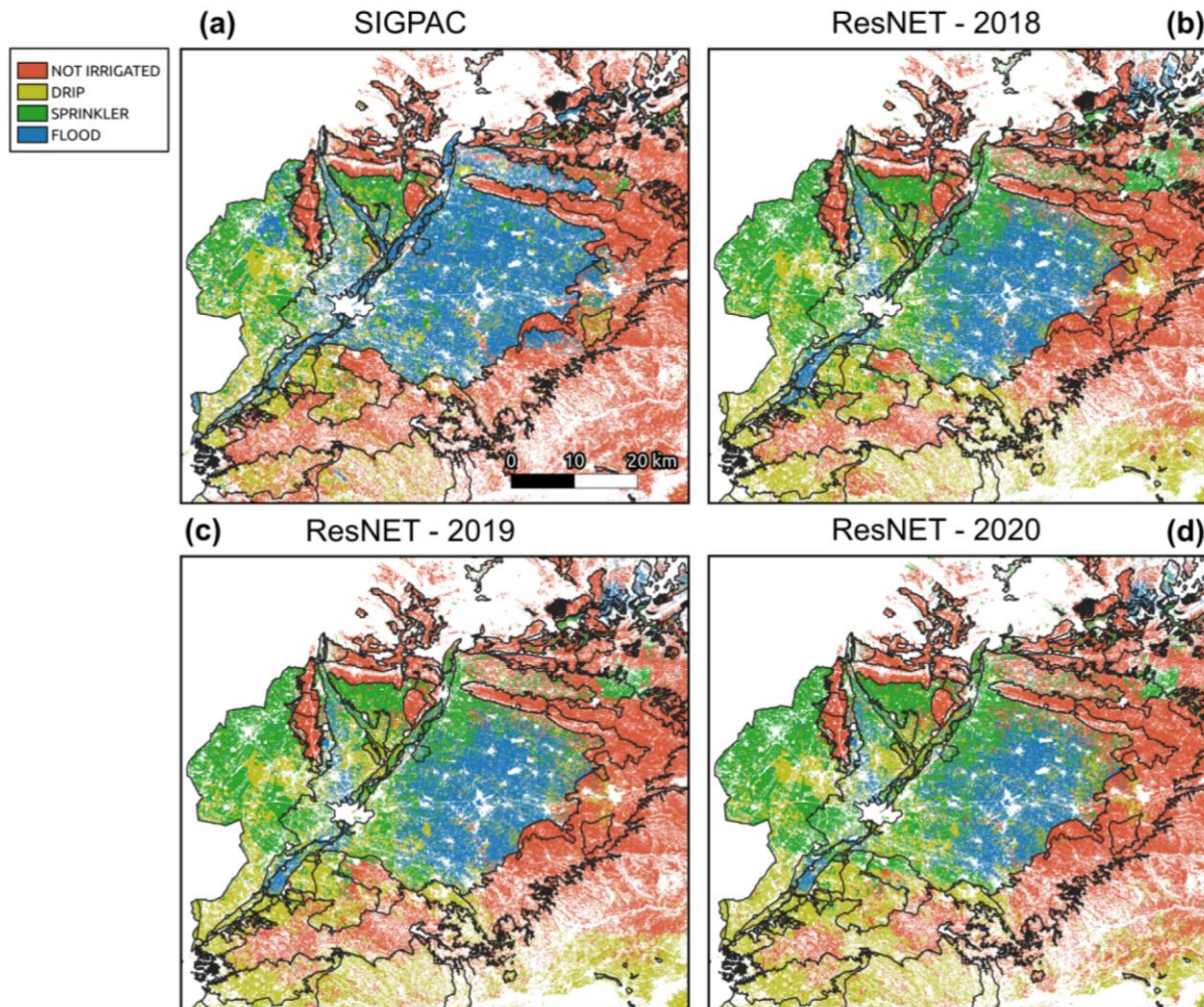
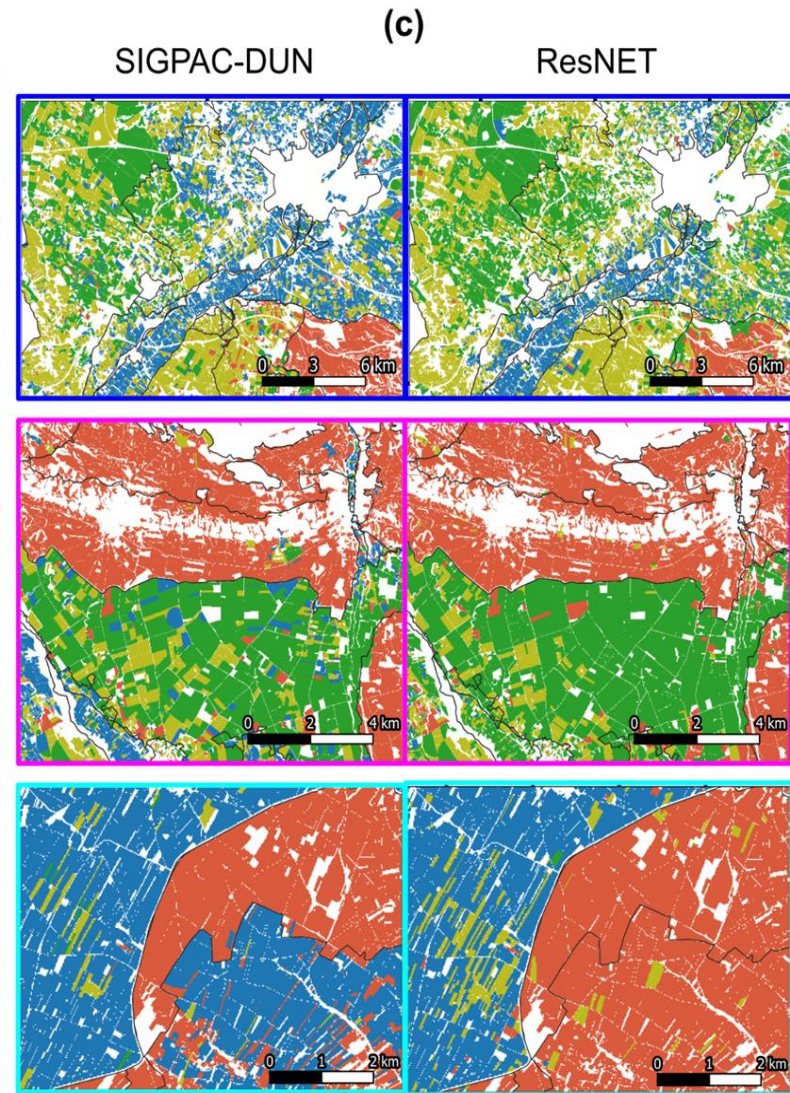
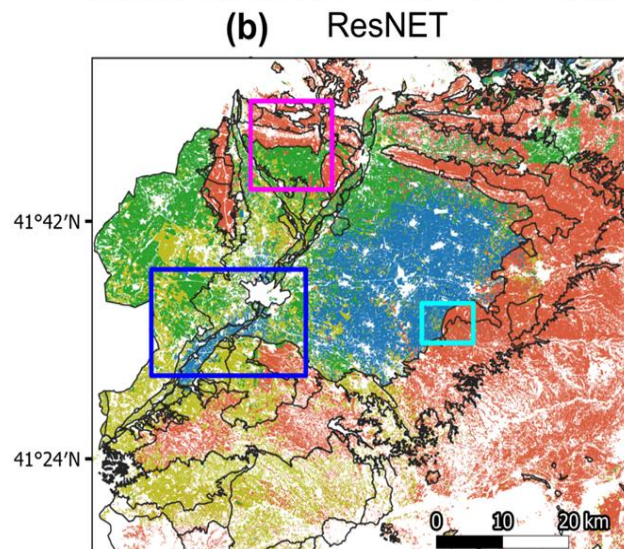
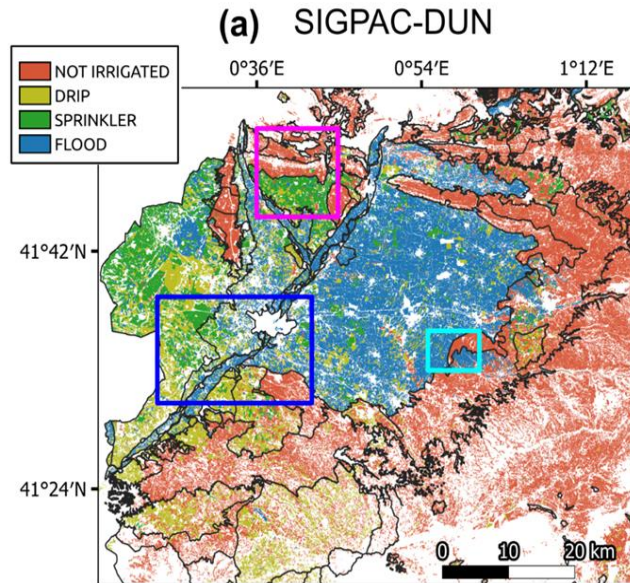
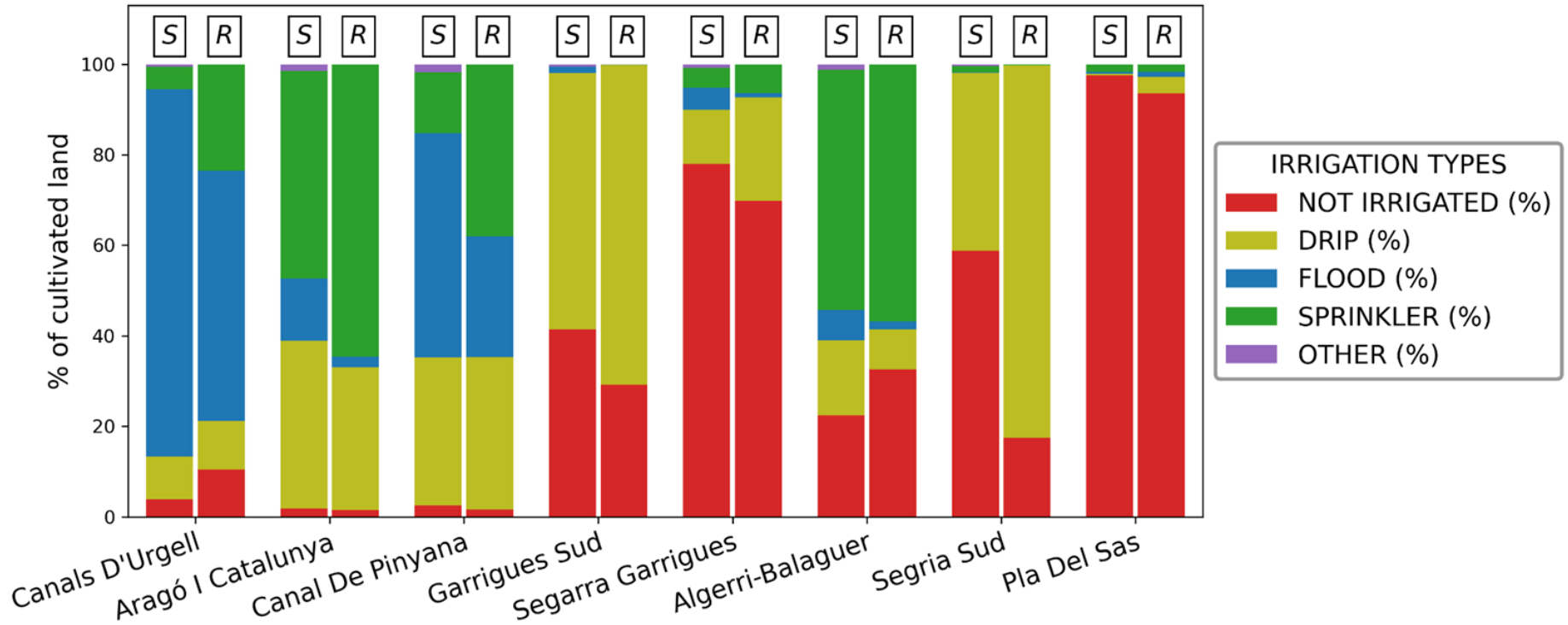


Figure 7: Irrigation Types map (a) as delivered by SIGPAC [34] and as created by the ResNET model with  $ET_a$  and  $SM$  time-series for 2018 (b), 2019 (c) and 2020 (d).

# Comparison: SIGPAC 2021

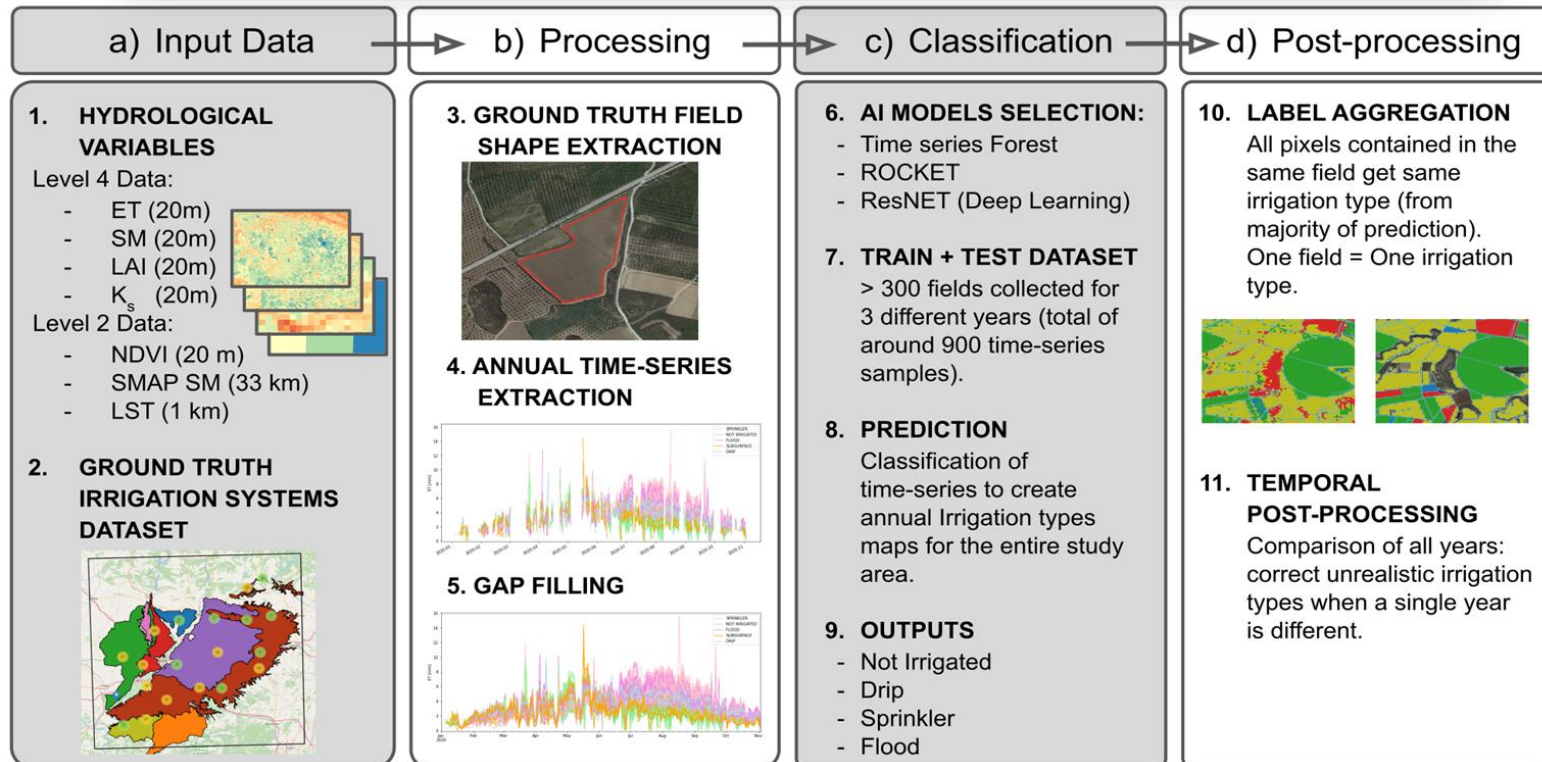


# Comparison: SIGPAC 2021



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**Thank you!**

**Any questions?**

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